

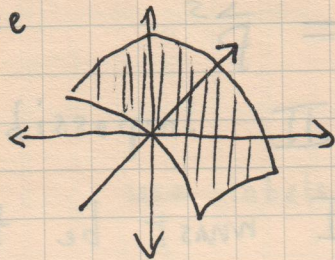
First step:

Take a classical dynamical system of  $N$  particles  
with  $\vec{q} = 3N$  coord. of all particles  
 $\vec{p} = 3N$  momenta of all particles

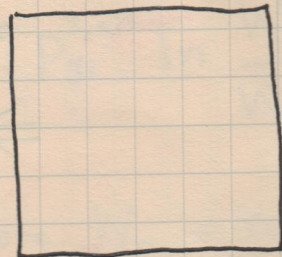
System confined to finite volume  $V$ , no  
gain/loss of energy from outside (isolated).

total energy  $E = H(\vec{q}, \vec{p})$  conserved  
↑  
Hamiltonian

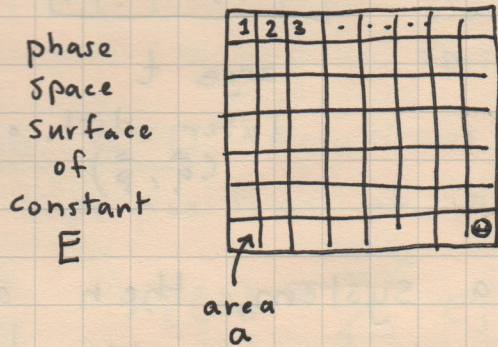
For a given  $E$ , the equation  $E = H(\vec{q}, \vec{p})$   
defines a  $6N - 1 \equiv D$  dimensional surface in  
phase space



→  
draw  
as  
square

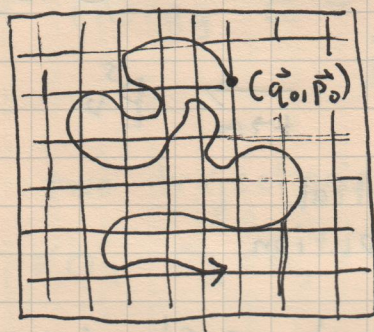


Divide up this constant energy phase space into area elements  ~~$\Delta$~~ , label them  $\nu = 1, \dots, \Theta(E)$   
of area  $a$  (small)



We say system is in "state"  $\nu$  if  $(\vec{q}, \vec{p})$  falls inside element  $\nu$

Classical mechanics starting w/ energy  $E$  at initial point  $(\vec{q}_0, \vec{p}_0)$  is a path on this surface.



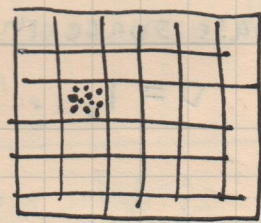
Keep in mind this system is deterministic!  
(no randomness assumed)

To justify stat. mech, we want a system where all trajectories (except maybe for a set of measure zero) are:

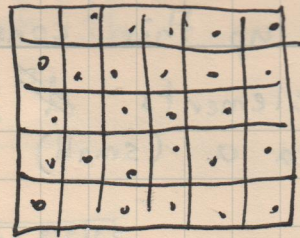
- ergodic: as  $t \rightarrow \infty$  every state  $\nu$  will be visited, no matter how small  $a$  is
- mixing: if at  $t=0$  several similar trajectories are initiated in <sup>any</sup> state  $\nu_0$ , they will diverge quickly (exponentially in time) so that when  $t \rightarrow \infty$  the  $(\vec{q}, \vec{p})$  ~~are~~ of these trajectories are distributed equally among all states  
(hallmark of a chaotic system!)

note:  
mixing is a stronger subset of ergodic

mixing:



$t=0$   
initial  
dist. of  $(\vec{q}, \vec{p})$



large  $t$   
later dist. of  
 $(\vec{q}, \vec{p})$

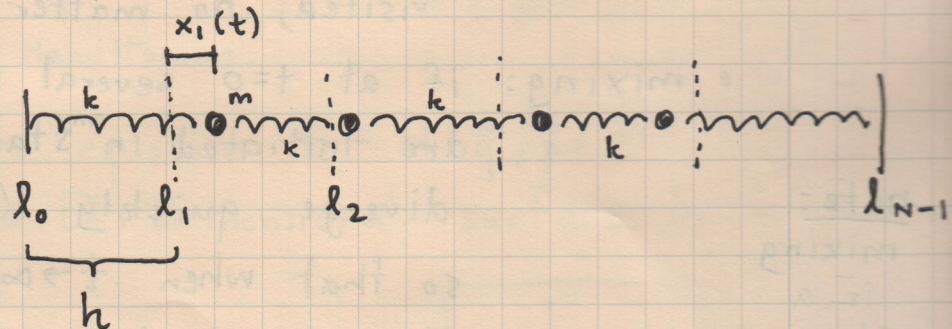
If one could find such a system, then one could generate a microcanonical ensemble by just waiting: a ~~collection of~~ stationary probability distribution  $P_V^S = \frac{1}{\Omega(E)}$  = same for all  $\downarrow$

Mixing entails  $P_V^i(t) \xrightarrow[t \rightarrow \infty]{} P_V^S$   
 $\uparrow$   
 any initial distribution

Not so easy to prove such systems actually exist!

1953-55: Fermi, Pasta, Ulam (FPU) and Tsingou conduct first ever physics computer simulation (on MANIAC I in Los Alamos) looking for this mixing behavior

Test system:  
coupled  
harmonic  
oscillators



spring constants  $k$

mass  $m$  at position  $X_i(t) = l_i + x_i(t)$

equations of motion:

$$m\ddot{x}_i = \underbrace{\left[ k(x_{i+1} - x_i) + k(x_i - x_{i-1}) \right]}_{\text{Standard spring forces}} \left[ 1 + \alpha (x_{i+1} - x_{i-1}) \right]$$

↑  
nonlinear  
perturbation

when  $\alpha = 0$ , solutions ~~have~~ can be written as superposition of normal modes:

$$x_i(t) = \sum_{j=1}^{N-2} c_j \xi_i^{(j)}(t)$$

$$\omega = \sqrt{\frac{k}{m}}$$

where  $\xi_i^{(j)}(t) = \cos\left(\frac{j\pi\omega t}{N-1}\right) \sin\left(\frac{ij\pi}{N-1}\right)$

total energy  $E = \sum_{j=1}^{N-2} \underbrace{c_j^2 E^{(j)}}_{\text{energy of } j\text{th mode}}$

Can choose two trajectories, one with

$$c_1 \neq 0, c_2 = 0, \dots, c_{N-2} = 0$$

other with

$$c_1 = 0, c_2 \neq 0, c_3 = 0, \dots, c_{N-2} = 0$$

and same  $E$ , and they will ~~never come close to each other~~ stay in separate parts of phase space, never mixing (energy in each mode a constant of motion)

$c_j(t)$  becomes time-dependent but { FPU tried  $\alpha \neq 0$ , creating "interactions" among modes, so energy (and amplitude) began spreading from one mode to another, but when they waited...

~~not all modes~~

all modes did not become equally likely, but the system followed complex quasiperiodic patterns

if you start 100% in mode 1, eventually return to case where 99% of energy is in mode 1, etc., and you never reach high  $j$  modes

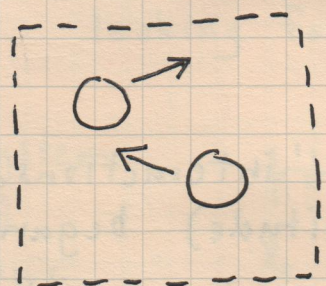
⇒ Major mystery! ⇒ no ergodicity, no mixing

1954-1963: Kolmogorov, Arnold, Moser (KAM) theorem proves that for weak interparticle interactions, quasiperiodic behavior persists near the unperturbed (zero interaction) trajectories.

To get ergodic + mixing you need strong interactions in a many particle system.

1970: Yakov Sinai (2014 Abel prize) makes breakthrough, proving that two hard disks on 2D square w/ periodic boundaries are ergodic + mixing.

(hard disk = ∞ repulsion on overlap = strong interaction)



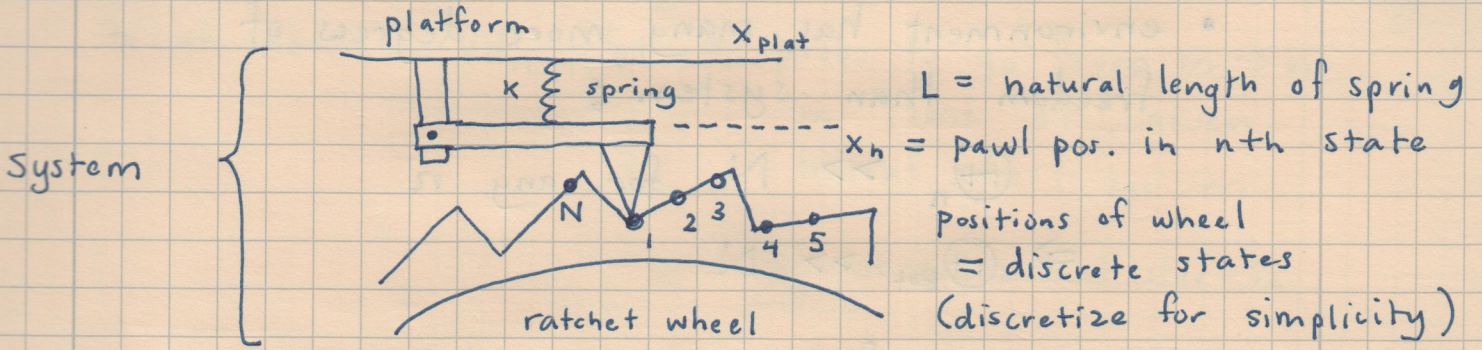
"Sinai billiard"

System exhibits chaotic trajectories, allowing for mixing

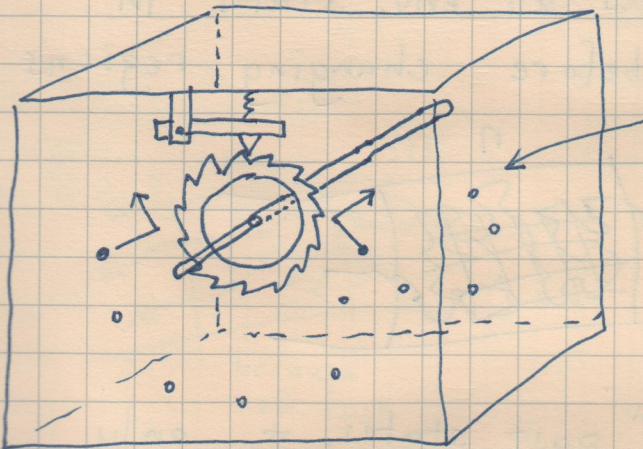
slow progress:  $N \geq 2$  d-dim. spheres is almost proven to be ergodic

To connect these ideas to matrix  $W$ , consider a "total" system composed of small subsystem (call simply "system") + rest (the "environment").

Famous example from Feynman: ratchet + pawl



system energy in state  $n$ :  $E_n = \frac{1}{2} k (x_{\text{plat}} - x_n - L)^2$



isolated box filled w/ fluid or gas ("environment")

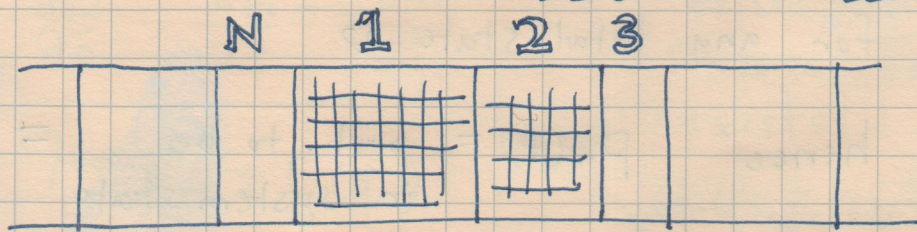
$$E_{\text{tot}} = E_n + E_n^{\text{env}}$$

$\Downarrow$  constant                       $\Uparrow$  energy of fluid when sys is in state  $n$

fluid particles can collide w/ system, exchanging energy by moving ratchet wheel

Assume the total is a strongly interacting, many particle system which is ergodic + mixing.

for total,  $E_{\text{tot}}$  manifold



all env. states when sys is in state 1

diff. regions correspond to diff. sys states

$\Omega_{tot} = \text{tot. number of states on } E_{tot} \text{ manifold}$

$\Omega_n = \text{number of states of the environment when system is in state } n$

Clearly  $\Omega_{tot} = \sum_{n=1}^N \Omega_n$

Assumptions:

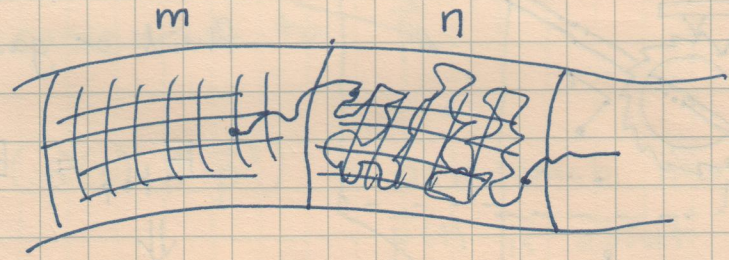
- environment has many more degrees of freedom than system :

$\Omega_n \gg N$  for any  $n$

$\Rightarrow \Omega_{tot} \gg N$

- mixing is fast : when a trajectory crosses from states  $m \rightarrow$  state  $n$  region, it quickly explores all env. states in state  $n$  region before changing regions

so each subregion of manifold mixes fast compared to  $\delta t$  of Markov description



$\Rightarrow$  Dynamics "forgets" past states, & only depends on current state in determining chance of transition at next time step

$\Rightarrow$  System is Markovian in previously defined sense.

- if we wait long enough,  $P_\nu(t) \rightarrow \frac{1}{\Omega_{tot}} \equiv P_\nu^s$  as  $t \rightarrow \infty$   
for any total state  $\nu$

hence  $P_n(t) = \text{prob. to be in system state } n = \sum_{\nu \text{ set corr. to } n} P_\nu(t) \rightarrow \frac{\Omega_n}{\Omega_{tot}}$

Thus an ergodic + mixing total physical system gives remarkable result for stationary probability:

$$P_n^s = \frac{\langle H_n \rangle}{\langle H \rangle_{tot}}$$

large compared to mixing time in each state

What about  $W_{nm} \delta t = \text{prob. to go from } m \rightarrow n \text{ in time } \delta t, \text{ given initial start in } m$

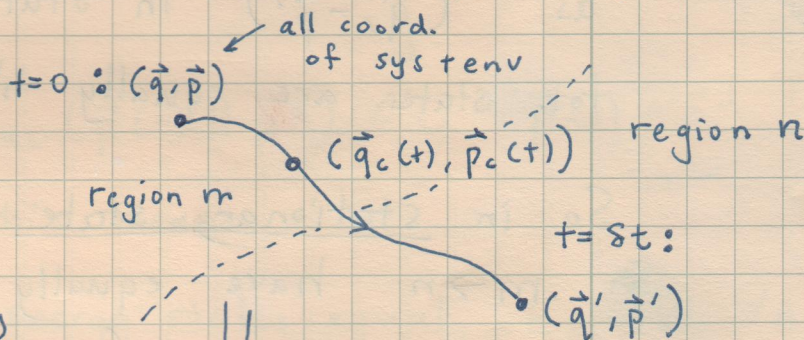
$$= \frac{\sum \text{all paths that start in } m}{\text{total paths}}$$

$$= \frac{\# \text{ classical trajectories that start in } m, \text{ end in } n \text{ after time } \delta t}{\# \text{ classical trajectories that start in } m, \text{ end anywhere after time } \delta t}$$



because of fast mixing, any starting point in m is equally likely

Very interesting property of classical trajectories: time reversal symmetry



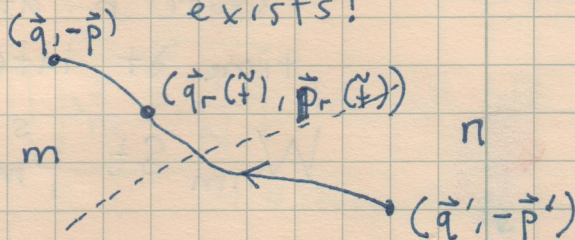
if such a trajectory exists, then "reverse" solution also exists!

Let Proof:  $(\vec{q}_c(t), \vec{p}_c(t))$  satisfy

Hamilton's equations:

$$\frac{d\vec{q}_c}{dt} = \frac{\partial H}{\partial \vec{p}_c}, \quad \frac{d\vec{p}_c}{dt} = -\frac{\partial H}{\partial \vec{q}_c}$$

with  $H = \frac{\vec{p}_c^2}{2m} + U(\vec{q}_c)$





then "reverse" solution

$$\vec{q}_r(\tilde{t}) \equiv \vec{q}_c(t-\tilde{t}), \quad \vec{p}_r(\tilde{t}) \equiv -\vec{p}_c(t-\tilde{t})$$

also obeys same equations of motion:

$$\mathcal{H} = \frac{\vec{p}_c^2}{2m} + U(\vec{q}_c) \rightarrow \mathcal{H} = \frac{\vec{p}_r^2}{2m} + U(\vec{q}_r) \quad \text{unchanged}$$

$$\frac{\partial \vec{q}_c}{\partial t} = \frac{\partial \mathcal{H}}{\partial \vec{p}_c} \rightarrow -\frac{d\vec{q}_r}{d\tilde{t}} = -\frac{\partial \mathcal{H}}{\partial \vec{p}_r} \quad \text{same}$$

$$\text{using } \frac{d\vec{q}_c(t-\tilde{t})}{dt} = -\frac{d\vec{q}_c(t-\tilde{t})}{d\tilde{t}} = -\frac{d\vec{q}_r}{d\tilde{t}}$$

$$\frac{\partial \vec{p}_c}{\partial t} = \frac{\partial \mathcal{H}}{\partial \vec{q}_c} \rightarrow \frac{d\vec{p}_r}{d\tilde{t}} = -\frac{\partial \mathcal{H}}{\partial \vec{q}_r} \quad \text{same}$$

$$\text{using } \frac{d\vec{p}_c(t-\tilde{t})}{dt} = -\frac{d\vec{p}_c(t-\tilde{t})}{d\tilde{t}} = \frac{d\vec{p}_r}{d\tilde{t}}$$

Note starting point  $(\vec{q}, \vec{p})$  is just as likely as  $(\vec{q}', -\vec{p}')$  in stationary state, b/c all tot. states are equally likely when  $t \rightarrow \infty$ .

So in stationary state all transitions from  $m \rightarrow n$  have equally likely reverse transitions from  $n \rightarrow m$ . (ensures microscopic reversibility)

prob. to see state  $m$ , then state  $n$  at time  $\delta t$  later = prob. to see state  $n$ , then state  $m$   $\delta t$  later

$$W_{nm} \delta t P_m^s = W_{mn} \delta t P_n^s$$

Hence

$$\boxed{W_{nm} p_m^s = W_{mn} p_n^s}$$

for any  
 $(n, m)$  where  
 $W_{nm} \neq 0$

↳ a property called  
detailed balance

Since  $p_m^s = \frac{\Theta_m}{\Theta_{\text{tot}}}$ ,  $p_n^s = \frac{\Theta_n}{\Theta_{\text{tot}}}$

⇒  $\frac{W_{nm}}{W_{mn}} = \frac{\Theta_n}{\Theta_m}$  useful property of  
 $W$  matrix entries

⇒ also ensures all networker are MR  
 (+ hence consistent w/ uniqueness of  
 $\vec{p}^s$ )