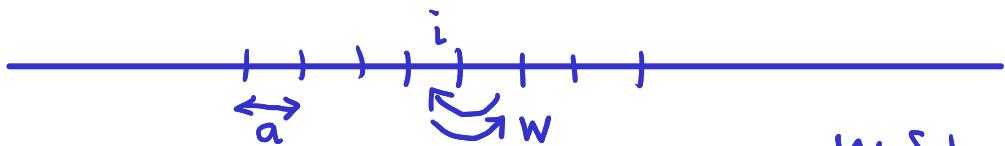


PHYS 320/420 Lecture 6

$$\text{MSD } \langle \Delta_i^2 \rangle_t = 2D t \quad D = wa^2$$



$w \delta t$ = prob to jump to
next box

D should be indep. of choice of a

$$\Rightarrow w = \frac{D}{a^2} \Rightarrow w \text{ increases as } a \text{ decreases}$$



$$\frac{dp_i}{dt} = \sum_j \Omega_{ij} p_j$$

to allow some solutions:

$$N \rightarrow \text{large}, \quad L = Na \quad (\text{length of our cell})$$

constant

$a \rightarrow \text{small}$

$$w = \frac{D}{a^2} \text{ increases}$$

define position $x = ia \rightarrow$ continuous variable

$$p_i(t) \rightarrow p(x, t)$$

RHS \rightarrow derivatives of p (not obvious!)

orig. master equations:

$$(1) \quad 1 < i < N : \quad \frac{dp_i}{dt} = -2w p_i + w(p_{i+1} + p_{i-1})$$

$$(2) \quad i=1 : \quad \frac{dp_1}{dt} = -w p_1 + w p_2$$

$$(3) \quad i=N : \quad \frac{dp_N}{dt} = -w p_N + w p_{N-1}$$

$$p_i(t) \rightarrow P(x, t)$$

$$p_{i+1}(t) \rightarrow P(x+a, t)$$

$$= P(x, t) + a \frac{\partial P}{\partial x} + \frac{1}{2} a^2 \frac{\partial^2 P}{\partial x^2} + \dots$$

$$p_{i-1}(t) \rightarrow P(x-a, t)$$

$$= P(x, t) - a \frac{\partial P}{\partial x} + \frac{1}{2} a^2 \frac{\partial^2 P}{\partial x^2} + \dots$$

$$(1) : \frac{\partial P(x, t)}{\partial t} = -2w \cancel{P(x, t)} + 2w \cancel{P(x, t)}$$

$$+ \underbrace{w a^2 \frac{\partial^2}{\partial x^2} P(x, t)}_D$$

$$\Rightarrow \boxed{\frac{\partial P}{\partial t} = D \frac{\partial^2}{\partial x^2} P}$$

diffusion equation

$$(2) \Rightarrow \frac{\partial P(a,t)}{\partial t} = -\cancel{wP(a,t)} + \cancel{wP(a,t)} + wa \frac{\partial P(a,t)}{\partial x} + \frac{1}{2} \underbrace{wa^2}_D \frac{\partial^2 P(a,t)}{\partial x^2}$$

Multiply both sides by a :

$$a \frac{\partial P}{\partial t} = \underbrace{wa^2}_{D} \frac{\partial P}{\partial x} + \frac{1}{2} a D \frac{\partial^2 P}{\partial x^2}$$

$\lim a \rightarrow \text{small}$:

$$0 = D \frac{\partial P}{\partial x}(0,t) \Rightarrow \boxed{\left. \frac{\partial P}{\partial x} \right|_{x=0} = 0}$$

bound. cond.

(3) Same argument:

$$i=N$$

$$x = Na \equiv L$$

$$\boxed{\left. \frac{\partial P}{\partial x} \right|_{x=L} = 0}$$

What do the solutions look like?

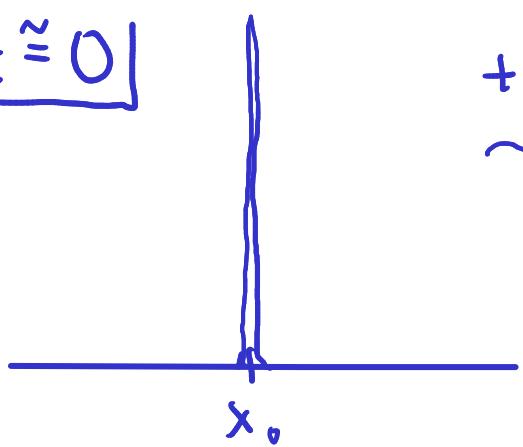
ignore boundaries (i.e. large cell)

focus on diff. equation + not bound. cond.

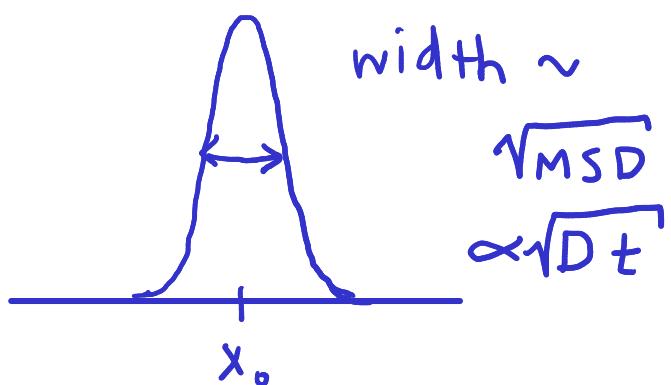
$$p(x,t) = \frac{1}{\sqrt{4\pi D t}} e^{-\frac{(x-x_0)^2}{4Dt}}$$

where initial cond: all systems start at x_0

$t \approx 0$



+ increases
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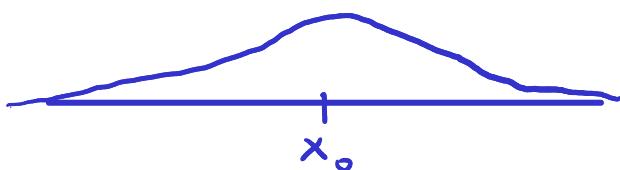


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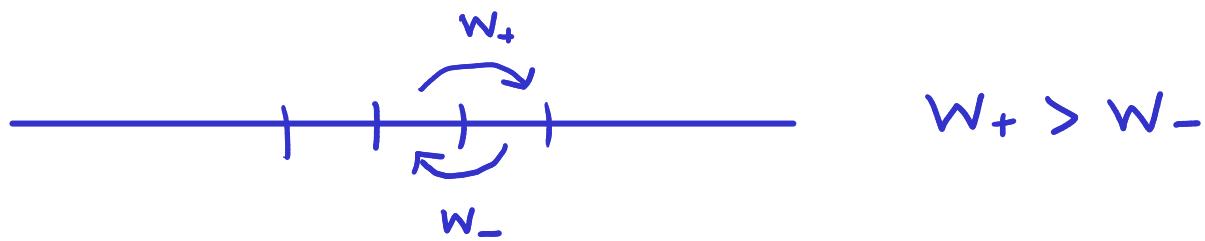
$$\sqrt{MSD} \\ \propto \sqrt{Dt}$$

$t$  inc.

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What happens if there is some overall flow to the right?



overall fluid speed: $v = a(w_+ - w_-)$

$\xrightarrow{\text{rel. of fluid}}$ \Rightarrow constant +

diff. Ω matrix =

$$\left(\begin{array}{c|c|c} -w_+ & w_- & \\ \hline w_+ & -(w_+ + w_-) & w_- \\ \hline & w_+ & \ddots \end{array} \right)$$

analogous steps: continuum approx

$$\Rightarrow \frac{\partial P}{\partial t} = -v \frac{\partial P}{\partial x} + D \frac{\partial^2 P}{\partial x^2}$$

Fokker-Planck equ.

$$P(x, t) = \frac{1}{\sqrt{4\pi D t}} e^{-\frac{(x - (x_0 + vt))^2}{4Dt}}$$

